

# Data monitoring and runtime process optimization

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# Synesis & role within I-ThERM



**SYNESIS** is a private-public **Consortium** whose main shareholders are private **Italian and German SMEs**, and whose public shareholders are Italian and German RTD Institutions: the **Italian National Research Council (CNR)** and the German **Fraunhofer Gesellschaft (FhG)**.

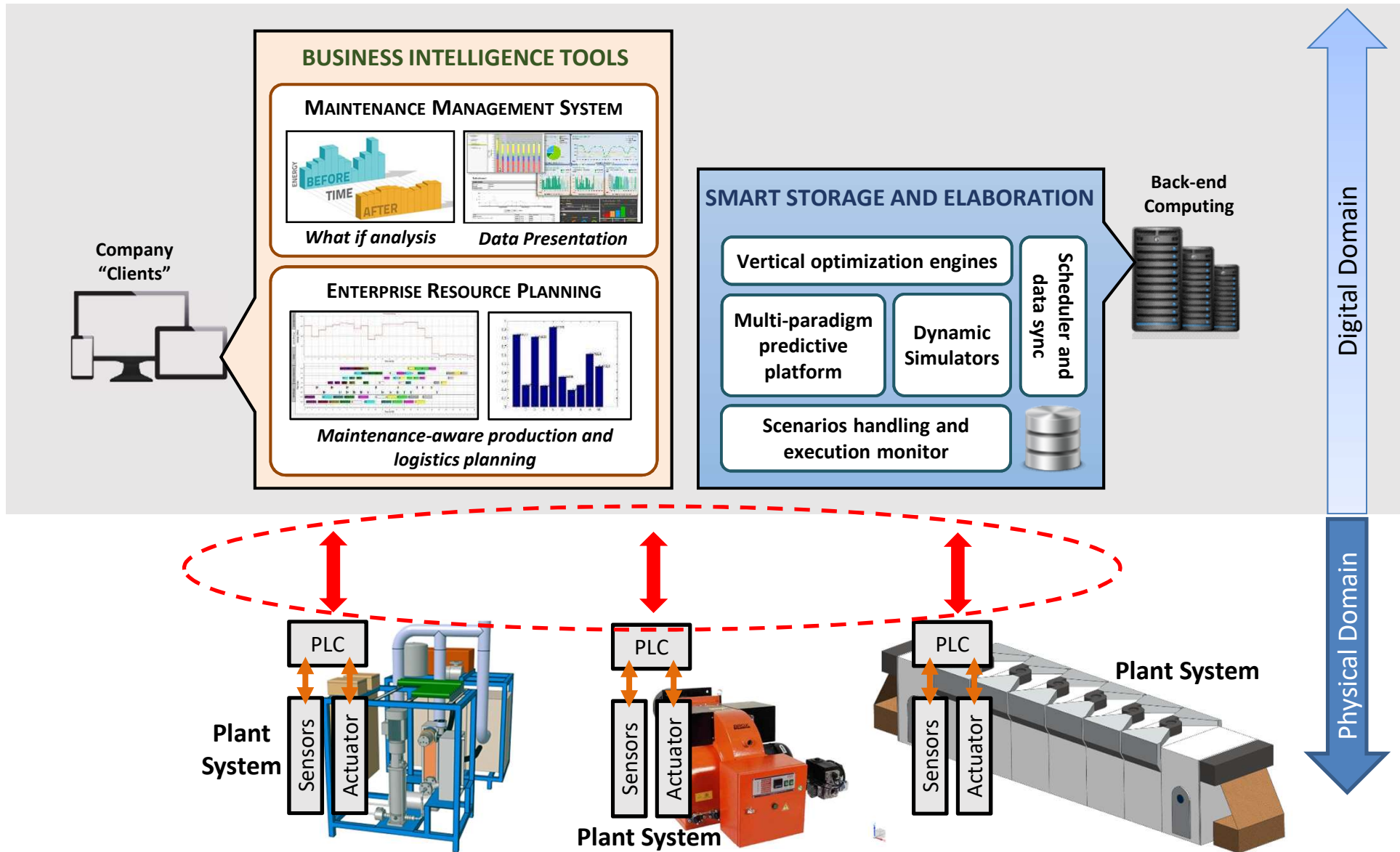


**MISSION** Synesis represents the new frontier of Technology Transfer in the industrial automation domain: bridging the gap between research and industry by mastering competences of both worlds

**INDUSTRIAL SECTORS** Research and Industrial initiatives for manufacturing technology innovation are focused on the concept of **Sustainable Automation**, merging seamlessly advanced control technologies with energy efficiency and low environmental impact.



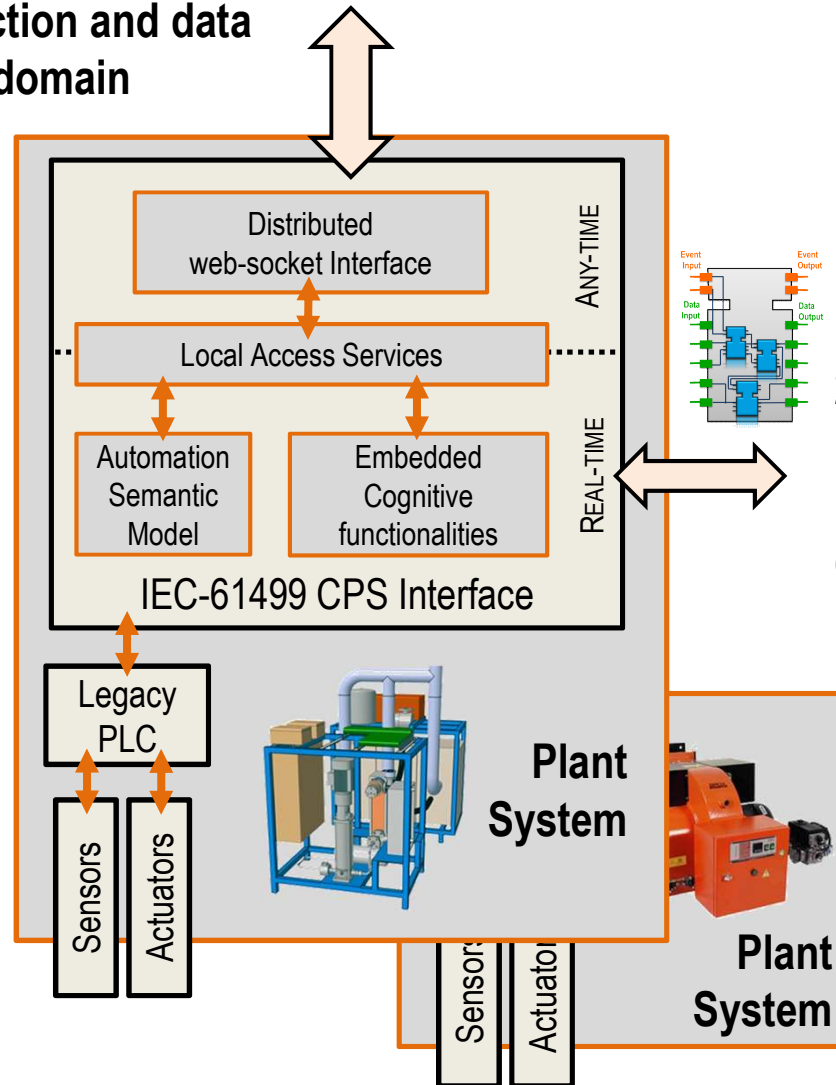
# Connection and supervision needs



# Communication, monitoring and supervisory control: high-level requirements

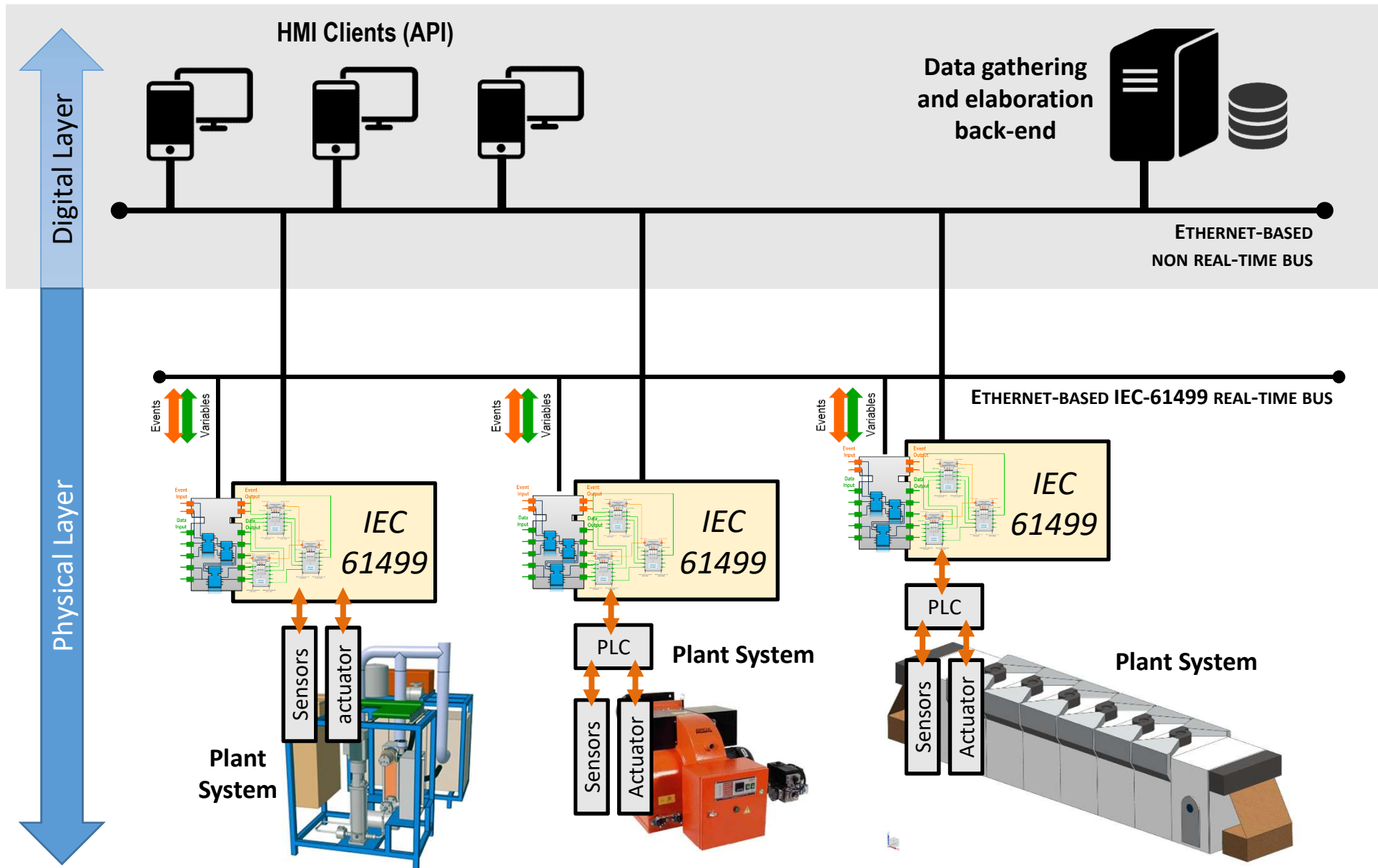
3. Full-duplex and event-based interface to enable seamless connection and data streams with ICT domain

1. Connection between a middleware node and PLC through standard interfaces (OPC-UA, Modbus, etc.)



2. IEC-61149 real-time communication to enable distributed elaboration of signals

# Communication, monitoring and supervisory control middleware: functional architecture



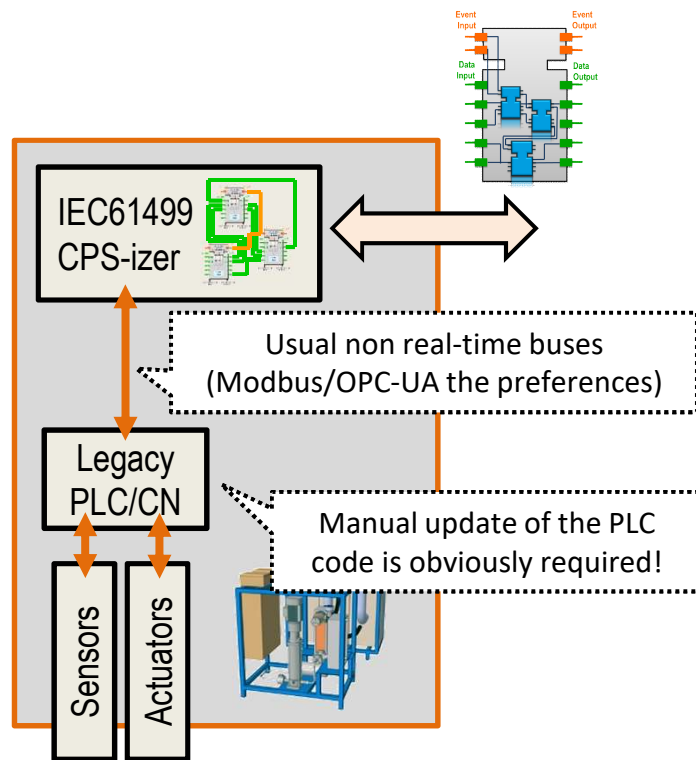
# Use-case scenarios and technical focus



## Interfacing with the plant systems

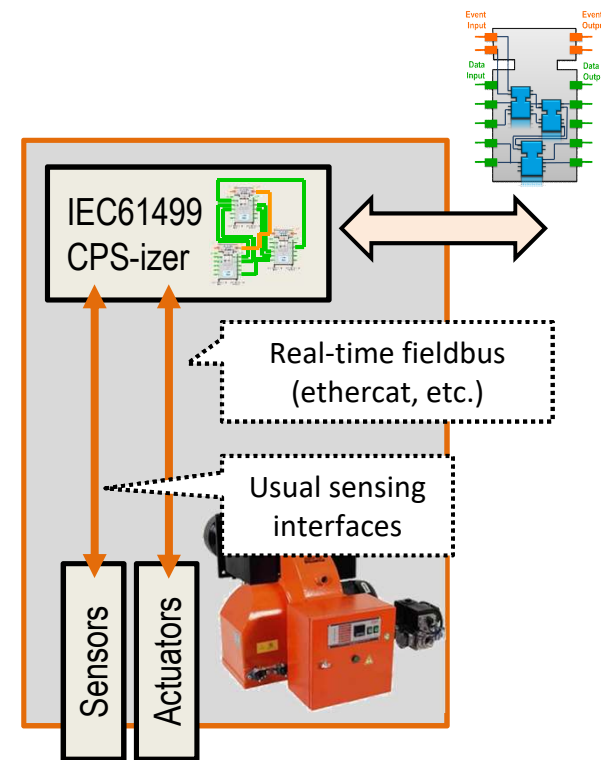
### *First scenario:*

*Communication with existing PLC (+CN) topology*



### *Second scenario:*

*Direct interfacing to new sensors and/or currently non-controlled devices*

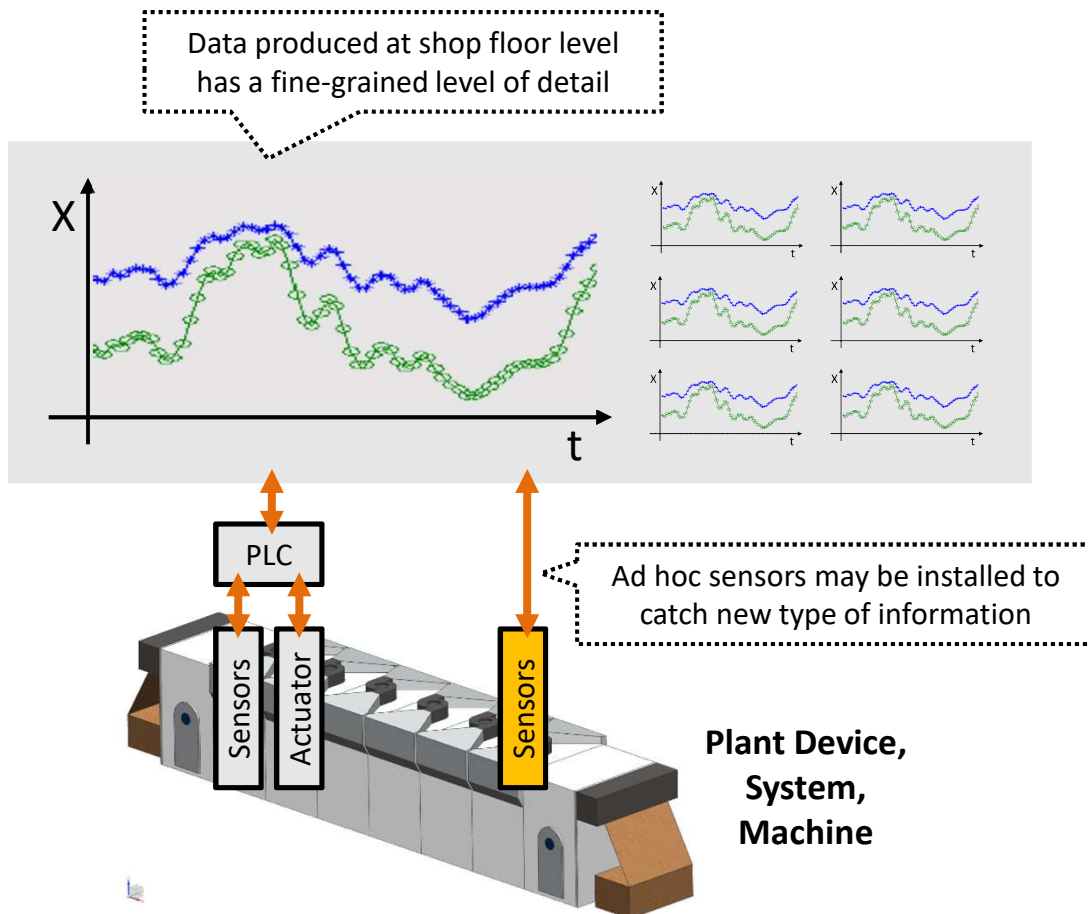


**All Nodes are IEC-61499 networked elements**

# Use-case scenarios and technical focus

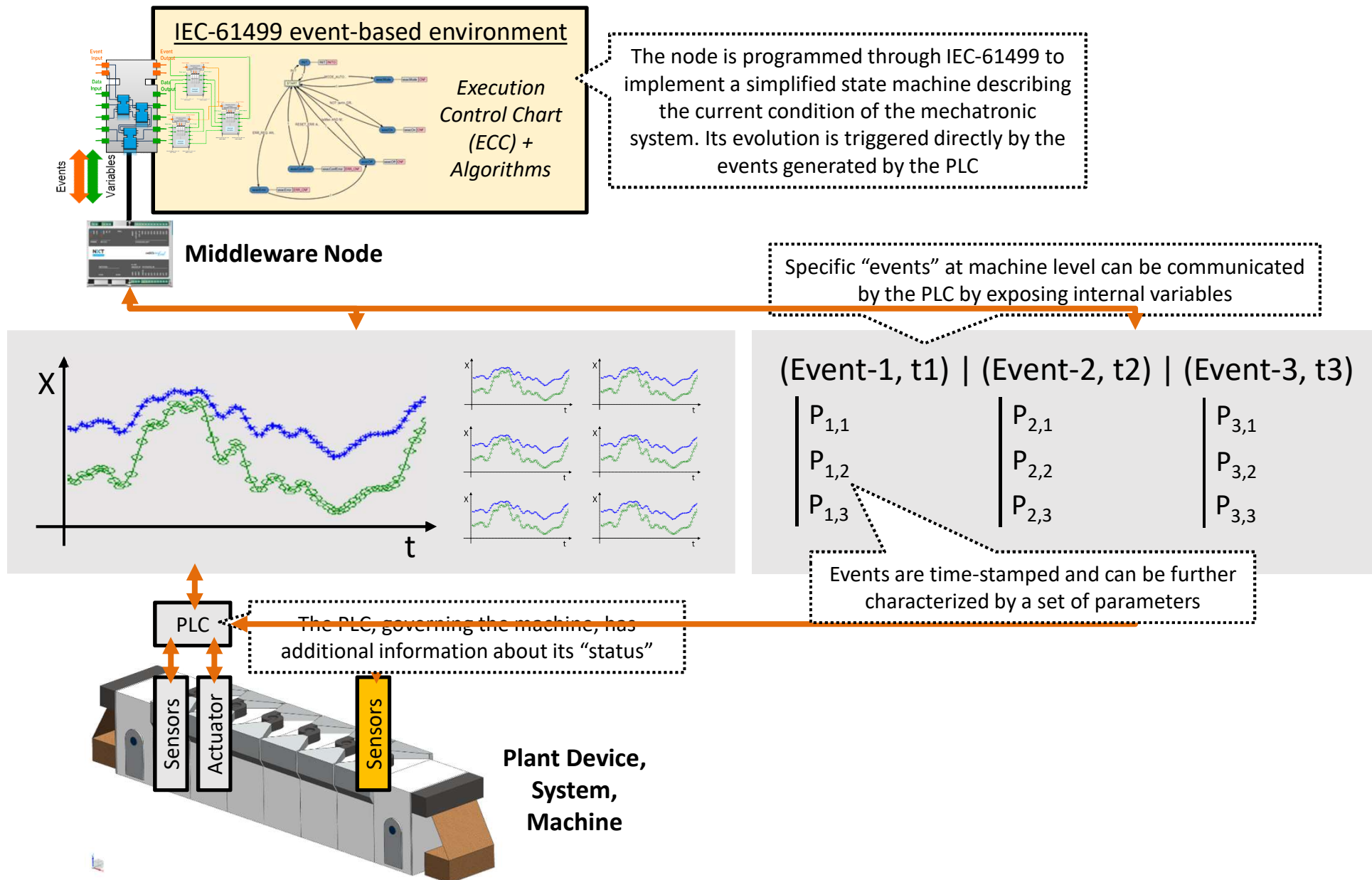
**Issue-1: bandwidth on the communication bus**

**Issue-2: raw data does not have contextual information**





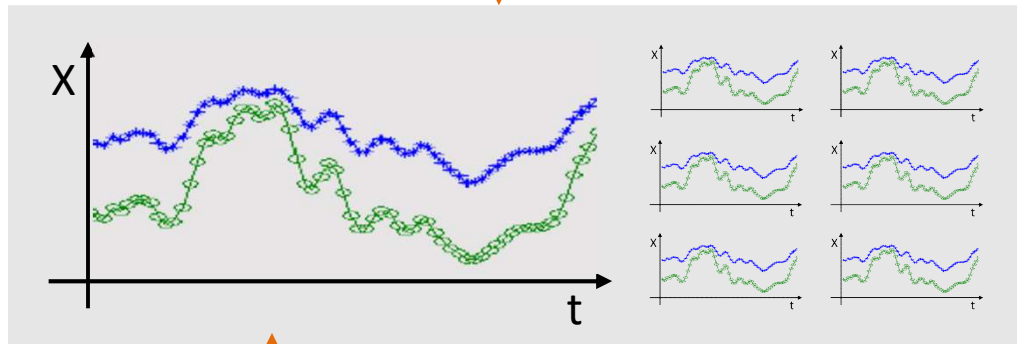
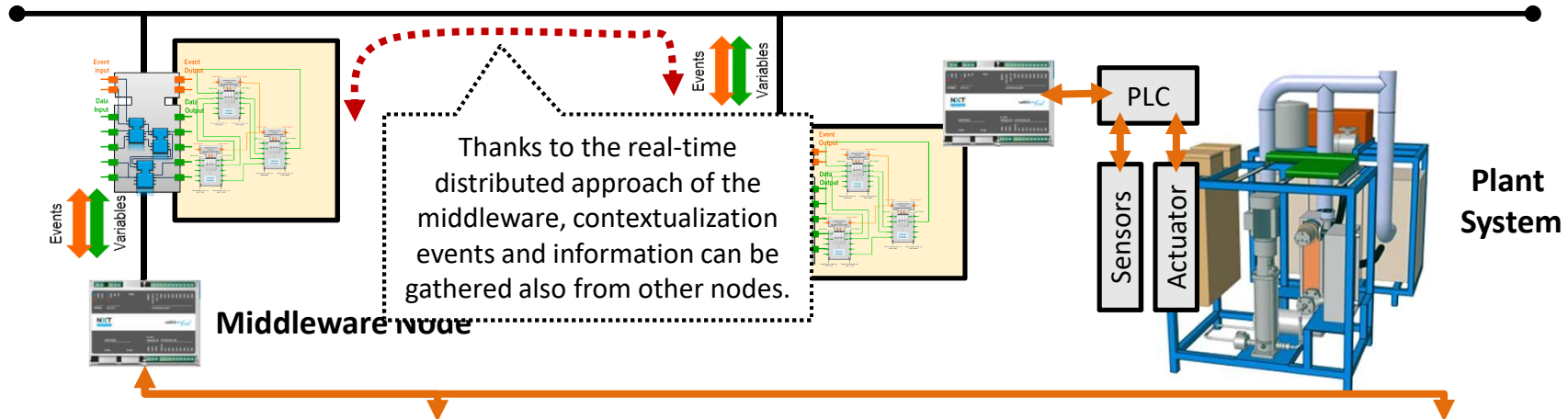
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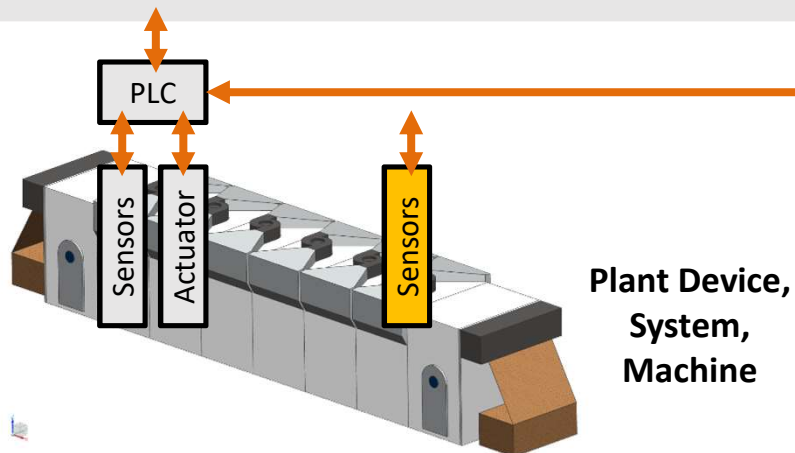
## ETHERNET-BASED IEC-61499 REAL-TIME BUS



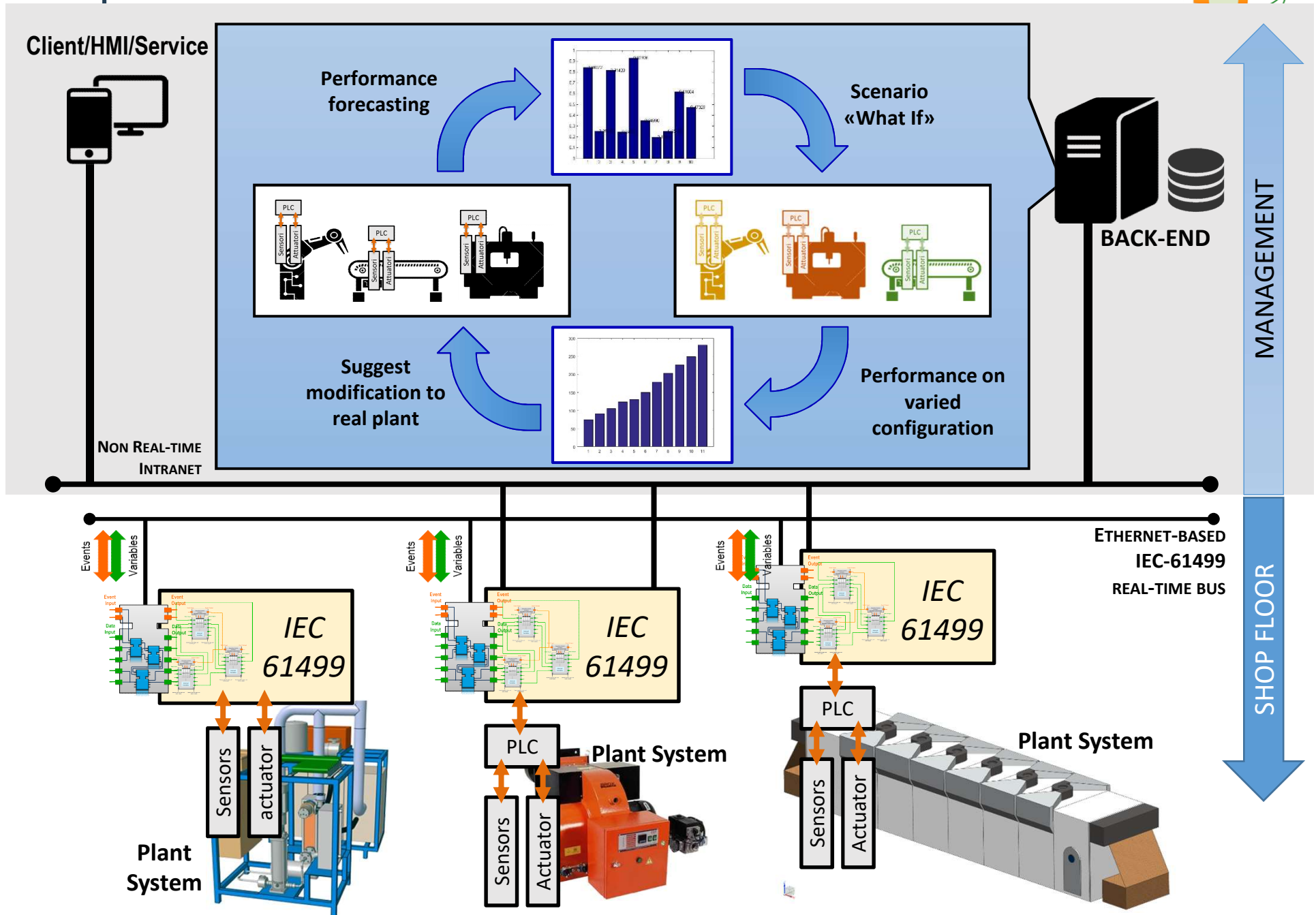
(Event-1,  $t_1$ ) | (Event-2,  $t_2$ ) | (Event-3,  $t_3$ )

$$\begin{vmatrix} P_{1,1} \\ P_{1,2} \\ P_{1,3} \end{vmatrix}$$

$$\begin{vmatrix} P_{2,1} \\ P_{2,2} \\ P_{2,3} \end{vmatrix}$$

$$\begin{vmatrix} P_{3,1} \\ P_{3,2} \\ P_{3,3} \end{vmatrix}$$


# Optimization and Control



# I-ThERM Demo - Heat pipe economiser

## ARLUY (WP7)

